26ο Θερινό Σχολείο – Συνέδριο «Δυναμικά Συστήματα & Πολυπλοκότητα» Εθνικό Μετσόβιο Πολυτεχνείο 15-19 Ιουλίου 2019

Ομοκλινικές συνδέσεις και η επίδρασή τους στην ασφάλεια πλοίων

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16 Ιουλίου 2019

Philosophy of approaches for predicting ship behavior at sea

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 x_0 y_0 z_0 y yz

Target: Ordinary behavior Emphasis: Accurate modeling Propulsion/environmental efficiency economy, comfort

Features:

- ✓ Quantitative ship geometry
- ✓ "First principles" hydrodynamics
- ✓ Mildly nonlinear
- ✓ Few simulations
- ✓ Time domain analysis

Target: Extremes, limits of safe behavior

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 $Z_{\rm S}, W$

Emphasis: Ship motion phenomena

 $y_{\rm s}$

Capsize, surf-riding, directional instability, parametric rolling, sudden heel during loading or due to symmetric water entry (loll), oscillations of moored vessels, sub-harmonic & chaotic motions Features:

- Intuitive modeling low-dimensional model approximations
- ✓ Ideal for understanding effect of nonlinearities

2

- $\checkmark\,$ Holistic in the dynamics
- ✓ Good for safety criteria development
- ✓ Analysis in *phase space*

Combines:

- Ship hydrodynamics
- Nonlinear dynamics stability theory
- Stochastic dynamics

The phase-space

Motions seen as a "flow" in the *phase-space*



For a nonlinear system, phase flow's geometry can be qualitatively changed as some influential parameter is varied



- Homoclinic: phenomena triggered by the contact of invariant manifolds formation of homoclinic or heteroclinic curves on Poincaré section of phase flow
- They modify globally the phase-space layout (change not in small neighborhood)
- Relate with **dynamic instabilities**
- Can explain unusual ship motions

Typical manifestations

- IMO's 2nd Generation Ship Stability Criteria address homoclinic phenomena
- abrupt disappearance of periodic behavior
- connected with ship capsize
- introduce motion irregularity



Energy dissipating system

The basin (domain) of attraction









4



Prediction tools

Direct simulation (= blind search)

Continuation (path - following): suitable for deterministic systems *Keller (1978), Rheinboldt (1980), Kubicek & Marek (1983), Doedel & Kernevez (1986), ...*

Melnikov's method: semi-analytical monitoring distance of invariant manifolds (for deterministic and stochastic systems) *Melnikov 1963, Wiggins 1990, Frey & Simiu 1993, ...* Works also as "energy balance" (Thompson 1997)

Lagrangian coherent structures: field methods

- Finite-time Lyapounov exponents (FTLE) Haller & Yuan (2000), Shadden, (2011) ...
- Finite-size Lyapounov exponents (FSLE) Artale et al. (1997), Koh & Legras (2002) ...
- Variational method Haller (2011)
- Extraction of coherent sets via clustering Froyland & Padberg-Gehle 2015



Summary of homoclinic phenomena in ship motions

Unforced ship:

→ Heteroclinic saddle connection modifies the **boundary of free** rolling, as heel bias is strengthened.

Regular waves:

- Beam-seas: Homoclinic and/or heteroclinic intersections enable capsize
- Following/quartering seas:
 - → Homoclinic saddle connection leads to global surf-riding and possibly to broaching-to
 - → Homoclinic saddle connection ends oscillatory surf-riding on wave down-slope.

Multi-chromatic/stochastic waves:

- Following/quartering seas:
 - → Heteroclinic intersections increase susceptibility for **broaching-to**.

Wind loading:

- Beam wind
 - → Homoclinic to saddle-node (omega explosion): barrier between straight-line motion and turning.

- Head wind:

→ Homoclinic saddle connection ends yaw oscillations (ship heading into wind with sluggish rudder control.



Basic (normalized) model for rolling with heel bias $\ddot{x}+b_1\dot{x}+b_3\dot{x}^3+x-(1-a)x^2-ax^3=f\sin\Omega t$ (2002) JSR, 46/3 Melnikov prediction: heteroclinic curve formed at: $a=1-\sqrt{2}b_1-\frac{12\sqrt{2}}{35}b_3$ (error <1%)

8

b) With harmonic forcing

The roll motion (cont'd)



Red: inset



9

JSR (2002) 46/3

The roll motion (cont'd)

Integrity diagrams (quintic restoring)



Forcing amplitude F

Effect of bias (cubic restoring)



Transient capsize diagram



The roll motion (cont'd)

Stochastic rolling: wave groups

Spectrum-compatible method of wave group construction Prob. Eng. Mech. 2015; Ocean Eng. 2016)

Markov chain model with cross correlations between heights and periods

Transition probabilities

most expected successions of height and period in group

Karhunen–Loève representation of wave elevation

$$\eta(x,t) = \sum_{n=0}^{\infty} a_n f_n(x,t), \quad -T < t < T$$

Sclavounos 2012, Proc. R. Soc. Lond. A468

Stability assessment in two parts:

Stochastic modelling
high probability realistic
wave group profiles

Ship motion simulations using derived waveforms Transient capsize diagram for regular and for realistic wave groups





The following/quartering sea

The broaching-to instability

✓ Uncontrolled, rapid deviation from desired course, sometimes ending with capsize

"The shipwreck"

Pollock (1810) (© National Maritime Museum, Greenwich)

inspired from Falconer (1762)

A topic with long history: reports date to 1699 (2010) Trans. RINA 152



Distinctive mechanisms JSR 1995, 40/3

- via surf-riding more common
- resonant yaw ("direct broaching-to")

Early scientific investigations:

Davidson (1948); Weinblum & StDenis (1950); DuCane & Goodrich (1962); Grim (1963), Wahab & Swan (1964); Boese (1970); Eda 1972; Motora et al (1982)



Conolly (1972) J. Mech. Eng. Sci., 14/7



heading (rad) -

How surf-riding behavior comes about?









Surf-riding in nonlinear waves

(Fenton's variant of Stokes wave theory)





Comparison of thresholds : linear versus nonlinear wave



Continuation result: homoclinic saddle connection





Surging and surf-riding in multi-chromatic seas



Spatiotemporal framework



(2016) 31st SNH

Nonlinear surge motions - bi-chromatic excitation



Comparative result from another ship with sharper separation of dynamics



Continuation result: arrangement of steady surf-riding states



wave steepnesss ratio r₂

-6.0 -8.0

Attracting (black) and repelling (grey) LCS -- JONSWAP spectrum

25 t = 300. s 20 الا 15 م X 10 5 600. 700. 800. x1 [m] 25 t = 410. s 20 [s/u] 15 X 10 5 2000. 2100. 2200. x1 [m] 25 t = 410. s 20 [m/s] Ř 10 5 2300. 2400. 2200. x1 [m]

Converting excitation from regular to irregular 25 t = 300 s 2.4 2.2 [1.8 1.6 1.4 1.4 0.8 0.6 0.4 0.2 a = 0.00 20 [s/u] 15 الا س X n 10 0. 0.4 0.6 0.8 1. 1.2 5 b2 = 0. frequency [rad / s] 2200 2300. 2400. x1 [m] 25 t = 300 s 2.2 a = 0.50 2. 1.8 1.6 1.6 1.4 20 18 (ສ ສ 15 amplitude 1.2 1. 0.8 0.6 [約16 14 MMMM Ž n 0.4 10 10 0.2 0. b2 = 0.50.4 0.6 0.8 1. 1.2 5 frequency [rad / s] 2200. 2300. 2400. x1 [m] 25 <u>t = 300 s</u> a = 1.00 0.6 20 [m] 0.4 0.2 18 [s/u] 15 [s/u] 14 ž 10 10 0. 5 b2 = 1. 0.4 0.6 0.8 1. 1.2 frequency [rad / s] 2200. 2300. 2400. (2016) 31st SNH x1 [m]

Behavior in irregular seas

21

Computation of local celerity







Maneuvering and course-keeping in strong wind

Maneuvering and course-keeping in strong wind (cont'd)



Final remarks

- ✓ Homoclinic phenomena are quite widespread in ship motions.
- ✓ Their investigation in multi-chromatic seas is the state-of-art topic, enabled by recent advances in computational techniques.
- ✓ Efforts to incorporate more detailed mathematical models should be strengthened.
- Excellent prospect for developing rigorous probabilistic assessments of ship stability-related problems.
- ✓ Efficiency issues exist due to combination of complex physics with rarity.
- ✓ Need to include relevant courses in naval architecture curricula.